spirax /sarco

SP300 Pneumatic Positioner

Description

The SP300 series is a microprocessor based positioner range that provides fast and accurate positioning of linear and rotary pneumatic actuated control valves. The instrument produces a pneumatic pressure output to accurately position the valve according to the input signal from external controller (4:20 mA) or from a bus network (Hart, Foundation Fieldbus, Profibus PA).

SP300 are compact and easy to maintain and operate. Local calibration and parameter setting can be done without the need for external devices.

Position Feedback (Fig. B)

The position of the valve is accurately measured using a magnetic sensor based on the "Hall effect", eliminating the need for feedback levers and potentiometers. This non contact feedback arrangement provides many advantages including improved reliability, safer operation, better accuracy and dead band because there are less moving parts subject to wear.

Operation

Output Module (Fig. A)

The main parts of the output module are: pilot, servo, Hall effect sensor and output control circuit.

The instrument CPU sends an electronic setpoint signal to the control circuit. The control circuit receives an actual valve position feedback signal from a Hall Effect sensor. By comparing the two signals the control circuit applies a voltage to the baffle (piezo) for the right valve positioning.

The pneumatic section is based on the well known nozzle-baffle and spool valve technology.

A piezoelectric disk is used as baffle in the pilot stage. The baffle is deflected upon receiving the voltage according to the required position change. A small variation of the air flow through the nozzle causes a change of pressure in the pilot chamber (pilot pressure).

Because pilot pressure is too low, with no flow capacity, it has to be therefore boosted. This is done in the servo section which acts as a transducer. The servo section has one diaphragm in the pilot chamber, and another smaller diaphragm in the spool chamber. The pilot pressure applies a force to the pilot side diaphragm which, at steady state, will be equal to the force that the spool valve applies to the smaller diaphragm.

When a change in position is required, pilot pressure increases or decreases as explained for the pilot stage. A change in pilot pressure forces the spool valve up or down changing the output 1 and the output 2 pressure until the desired position is reached.





Fig B Magnetic Sensor



The mounting arrangement for linear actuators complies with IEC534-6 The mounting arrangement for rotary actuators complies with VDI/ VDE3845

The "Hall effect" sensor can be remotely mounted upto 65 ft from the instrument. This is particularly useful for applications subject to high ambient temperatures or heavy vibration.

Local regulation may restrict the use of this product below the conditions quoted. Limiting conditions refer to standard connections only. In the interests of development and improvement of the product, we reserve the right to change the specification.

SP300 Pneumatic Positioner

Models & Protocols

The communication protocols of all SP300 are industry standard, which means they are easily interfaced with the control system and therefore reduce installation and maintenance costs.



SP 301 4 to 20 mA + HART® Valve Positioner

The SP301 microprocessor based pneumatic valve positioner

operating in a current loop system. It produces a pressure output as required to position a control valve according to a 4 to 20mA input signal. The communications of the SP301 are based on the HART® protocol. Calibration and setting of parameters can be carried out via local adjustment or using portable equipment as a PDA with HART interface or with a PC including HART® software.

SP 302 Foundation Fieldbus Valve Positioner



The SP302 is a Foundation Fieldbus device. It is a microprocessor based pneumatic valve positioner operating in a Fieldbus system.

The SP302 produces a pressure output as required to position a control valve according to an input received over the Fieldbus network.

Calibration and setting of parameters can be carried out via local adjustment or using a remote configurator (es. Syscon)

SP 303 PROFIBUS PA Valve Positioner

The SP303 is a Profibus PA device. It is a microprocessor based pneumatic valve positioner operating in a Fieldbus system.

The SP303 produces a pressure output as required to position a control valve according to an input received over the Fieldbus network.

Calibration and setting of parameters can be carried out via local adjustment or using a remote configurator (es. PDM Simatic)

Specific Technical Features

SP 301

Communication Protocol HART® (is superimposed on the current signal)

Input Signal Two-wire, 4 to 20 mA controlled according to NAMUR NE43 Specification, with superimposed digital communication (HART® Protocol)

Power Supplied by the 4 to 20 mA current. No external supply required.

Voltage drop 11 Vdc max / 20 mA (equivalent to 550 W) Mininum current 3.8 mA

Reverse Polarity Protection Is provided to prevent internal circuit damage in the event of reversal of the 4 to 20 mA supply signal.

SP 302

Communication Protocol Foundation™ Fieldbus.

Input Signal Digital only. Foundation[™] Fieldbus, complies with IEC 1158-2 (H1): 31.25 Kbit/s and voltage mode with bus power. **Voltage drop** Bus powered: 9 to 32 Vdc. Quiscent current consumption 12 mA

Function Blocs:

RES	- Resource	TRD - Transducer
DSP	 Display transducer 	DIAG - Diagnostics Transducer
PID	 PID Control 	EPID - Enhanced PID
AO	 Analog Output 	ARTH- Arithmetic
INTG	- Integrator	ISEL - Input Selector
CHAR	 Signal Characterizer 	SPLT - Splitter
AALM	 Analog Alarm 	SPG - Set Ramp Generator
TIME	- Timer	LLAG - Lead-Lag
OSDL	 Output Selector / 	CT - Constant
-	Dynamic limiter	

SP 303

Communication Protocol PROFIBUS PA.

Input Signal Digital only. PROFIBUS PA, commplies with IEC 1158-2 (H1): 31.25 Kbit/s and voltage mode with bus power. Power Supply Bus powered: 9 to 32 Vdc / Quiescent current con-

supprior 12mA.

Output impedance (from 7.8 to 39 kHz). Function Blocs: PHY - Physical

ion Blocs:	PHY - Physical	TRD - Transducer
	DSP - Display	AO - Analog Output

Common Technical Features

Functional Specifications

- TravelLinear Motion:1/8" (3 to 100 mm)Rotary Motion:3 to 120° Rotation angle
- Output Signal

Output to actuator 0 to 100 psig supply air pressure. Single or double action.

Pressure Supply

1.4 to 7 barg (20 to 100 psig).

Free of oil, dust and water.

Indication

41/2-digit LCD indicator and 5 alphanumeric characters.

Hazardous Location Certification

Explosion proof, weather proof and intrinsically safe from ATEX, CSA, FM.

Temperature Limits

remperature Em	11.0		
Operation: -40 to	185°F (-40 to 85°C)		
Storage: -40 to -	194°F (-40 to 90°C)		_
Display: 14 to 14	10°F (-10 to 60°C) operat	ion	
-40 to 1	85°F (-40 to 85°C) withou	ut damage.	
Humidity Limits	Turn-on Time	Update Time	
0 to 100% RH.	Approx. 10 seconds	Approx. 0.2 seconds	

Flow Characterization

Linear, Equal Percentage, Quick Opening, 16 freely selectable points. Through software or locally adjustable.

Gain Through software or locally adjustable.

Travel Time

Through software or locally adjustable.

Actual Position Sensing

Magnet sensor (non contact) via Hall effect.

Performance Specifications

Sensitivity / Resolution	Repeatability		Hysteresis
≤ 0.1 % F.S.	_< 0.1 % F.S.	_	< 0.1 %
F.S. (Full Scale)			
Consumption			
0.25 Nm3/h (0.15 SCFM)	at 1.4 barg (20 psi	g) suppl	ly.
0.70 Nm3/h (0.40 SCFM)	at 5.6 barg (80 psi	g) suppl	ly.
Output Capacity			-
46.7 Nm3/h (28 SCFM) at	t 5.6 barg (80 psig)	supply.	
Ambient Temperature E	ffect		
0.8% / 20°C (68°F) of spa	ın.		

Supply Pressure Effect

Negligible.

Vib	rat	ion Effe	ct		
± 0	.3%	₀ / g of s	pan durin	g the following conditions:	
5	to	15 Hz	at 4 mm	(1/8") constant displacement;	
15	to	150 Hz	at 2g;		
150) to	2000 Hz	z at 1g.		

Reference SAMA PMC 31.1 1980, Sec. 5.3, Condition 3, Steady State.

Electro-Magnet Interference Effect

Designed to comply with IEC 61326: 2000.

Physical Specifications

Electrical Connections	1/2" - 14 NPT, Pg 13,5 or M20 x 1,5.
Pneumatic Connections	Supply and output: 1/4" - 18 NPT.
	Gauge: 1/8" 27 NPT.

Material of construction

Injected low copper aluminium with polyester painting or 316 stainless steel housing, with Buna N 'O'rings on cover (NEMA 4x, IP 67)

Weight

Weight	
Without display and mounting bracket:	Std. body 2.7 kg (6 lbs)
	SS body 5.8 kg (12.8 lbs)
Add, for digital display:	0.1 kg (0.22 lbs)

ositioners & Switches



Local Display Drawing

all SP300 positioners are fitted with a digital indicator that allows you to:

- read the parameters
- set the parameters
- read the diagnostic messages
- read measured values





Configuration / Connection Diagram

Rotary

Magnet

In Foundation Fieldbus or Profibus PA configuration



Ø69 (2.72) Ø21 (0.83)

Dimensions

Valve Positioner







Linear Magnet

Travel Up to 15 mm Up to 30 mm Up to 50 mm

Up to 100 mm

Dimension A 44 mm 50 mm 109 mm 185 mm

(0.87) (0.5

6,5 (0.25)



TI-P370-19-US 5.06

SP300 Pneumatic Positioner

SP30	Pos	fitioner w	ith digi	tal displa	у			
	<u> </u>	4	- 20 mA + Hart					
	2	Fo	oundation Fieldbus					
	*3	Pr	Profibus PA					
		Su	Bracket Mounting Kit **					
		0		With kit	KII (hracké	et + magnet)		
			:	Suffix	Elect	rical Connection	tions	
			! [*0	1/2-	14 NPT		
				A	M20	x 1,5		
			¦	<u>в</u>	PG 1 Suffi		Actuator **	
			1		*1	Rotary	- Single Action	
			1		2	Rotary	- Double Action	
					*3	Linear	- Single Action	
			1		4	Linear Other Sp	- Double Action	
						Suffix	Indication Gauge	
			i i			0	Without Gauge	
						1	With Gauge - input	
			i i			2	With Gauge - Output 1 With 2 Gauges - input and Output 1	
						4	With 2 Gauges - Output 1 and 2	
			i i			5	With 3 Gauges	
			1			Z	Other Specify	
			i i				H1 316 SST Housing and body	
	- i		1		i		R1 Remote sensor	ves
			1				I2 Explosion Proof (ATEX)	Cor Val
	- i				į		I4 Intrinsically Safe (ATEX)	
			!				SZ Specify special application	
	1			i	i			
							Typical positioner model:	ers Jes
	SP3	301	1	0	3	3	I2 4-20 mA signal+HART protocol - 1/2" NPT electrical connection - single	itio
Note 1	: Posit	tioners ar	e alway	/s Explosi	on Proo	f. Intrinsically Sa	Safe. FM action linear valve -2 gauges - digital indicator - Explosion Proof (ATEX) label	Sw
and CS	SA cert	tified: 12-	13-14-1	5suffix ar	e for lat	bel identification	n. <u>Alterdard</u> ** Ne energy al susilable	പ്യ
							Standard in No approval available	
К	MS E	Bracket	/ Magn	et Kit				
		Suffix	Brack	et Kit				
)	Witho	ut Positio	oner Bra	acket		
		 >	Unive	rsal Line	iry ar (Yoki	e and Pillar)		
	*	3	Linea	r Spirax S	Sarco V	alves		
	4	1	Rotar	y Spirax	Sarco V	/alves		
		<u>Z</u>	Other - Specify					
	1		0	Rota	Irv			
	i –		*1	Line	ar Up to	o 15 mm		
	1		*2	Line	ar Up to	30 mm		
	1	1		Line	ar Up to ar Un to	0 50 mm		
	1		Z	Othe	er - Spe	cify		
	i –			Suffi	x M	ounting Brack	ket Material	
	1			*C	C	arbon Steel Br	Bracket	
	į.	!	İ		0	ther - Specify		
	1	i		<u> </u>	S	uffix Option	onal Item	
	!		į		S	YZ Speci	cify Actuator Model / Company	
KM	S	3	2	I		000	Typical Kit model: Stainless Steel bracket for Spirax Sarco linear	
			_	1			valve - magnet for up to 30 mm valve stroke - Yoke & Pillar mounting,	
*	Stand	dard					ngni side, <u>sidek odde s700300</u>	

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